# $\mathbf{A ~ P B P O}^{+}$Graph Rewriting Tutorial 

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#### Abstract

We provide a tutorial introduction to the algebraic graph rewriting formalism $\mathrm{PBPO}^{+}$. We show how $\mathrm{PBPO}^{+}$can be obtained by composing a few simple building blocks. Along the way, we comment on how alternative design decisions lead to related formalisms in the literature, such as DPO.


## 1 Introduction

Graphs are useful data structures for virtually every field of computer science. And they come in many varieties: they can be directed or undirected, may carry labels or attributes, the edges can be hyperedges, and so on. Computation on these graphs is however similar, and can be roughly described as the stepwise replacement of subgraphs, induced by a set of replacement rules. For this reason, it is helpful if the replacement mechanism can be defined in a general way, without having to commit to a particular notion of a graph. Ehrig et al. [9] first managed to do so in the 1970s, by specifying a replacement mechanism (namely, Double Pushout (DPO) rewriting) in the language of category theory. Their seminal work laid the foundation for the field of algebraic graph rewriting [7], in which a variety of categorical graph replacement mechanisms have been proposed and studied.
$\mathrm{PBPO}^{+}[14]$ (short for Pullback-Pushout with strong matching) is a graph rewriting formalism in this algebraic tradition, obtained by adding a strong matching requirement to PBPO [4]. One feature of $\mathrm{PBPO}^{+}$is that it is expressive: in the abstract setting of quasitoposes, $\mathrm{PBPO}^{+}$has been shown [15] to subsume other well known formalisms such as DPO [9], SqPO [5], AGREE [3] and PBPO. Quasitoposes include various graph-like categories such as the categories of labeled multigraphs, hypergraphs, safely marked Petri nets and simple graphs; as well as various categories that are not graph-like.

In this tutorial, we introduce $\mathrm{PBPO}^{+}$in a stepwise manner, starting from minimal preliminaries. In particular, we do not assume an understanding of category theory or related formalisms. Instead, we introduce two toy formalisms ToyPO (Section 2) and ToyPB (Section 3), and show how $\mathrm{PBPO}^{+}$can be understood as a combination of the two (Section 4). Our approach complements existing tutorials for related formalisms (Section 5).

Preliminaries. We write $f \circ g$ to denote function composition $((f \circ g) x=f(g(x)))$. By a graph $G$ we mean an unlabeled directed multigraph, i.e., $G=(V, E, s, t)$, where $V$ is a set of vertices (or nodes), $E$ a set of edges, $s: V \rightarrow E$ a source function and $t: E \rightarrow V$ a target function. A graph homomorphism $\phi: G \rightarrow H$ from graph $G$ to graph $H$ is a pair of functions $\phi_{V}: V_{G} \rightarrow V_{H}$ and $\phi_{E}: E_{G} \rightarrow E_{H}$ satisfying $\phi_{V} \circ s_{G}=s_{H} \circ \phi_{E}$ and $\phi_{V} \circ t_{G}=t_{H} \circ \phi_{E}$. We use $\hookrightarrow$ to denote injective homomorphisms, and $A \cong B$ to denote that $A$ and $B$ are isomorphic.

A note on vocabulary. A category consists of objects and morphisms between them. In our graph setting, these instantiate to graphs, and graph homomorphisms between graphs, respectively. We state some concepts (such as pushouts and pullbacks) categorically in this paper, but readers unacquainted with category theory may safely read "graph" for "object" and "graph homomorphism" for "morphism".

## 2 ToyPO

We start by defining a toy graph rewrite formalism called ToyPO (short for ToyPushout). This formalism computes rewrite steps using a single pushout construction. It allows the specification of identification and addition of elements.
Definition 1 (ToyPO Rule). A ToyPO rule is a morphism $\rho: L \rightarrow R . L$ and $R$ are called patterns.
Example 1. The rule $\rho: L \rightarrow R$ depicted by (a) $\longrightarrow$ (b) $\xrightarrow{\rho}$ (ab) (c) can be described as specifying (i) the identification of two connected nodes $a$ and $b$, and (ii) the addition of a node $c$.
Notation 1 (Visual Notation). Our notation for graphs and graph homomorphisms can be described formally. A vertex is a non-empty set $\left\{x_{1}, \ldots, x_{n}\right\}$ represented by a box $x_{1} \cdots x_{n}$, and each morphism $f=\left(\phi_{V}, \phi_{E}\right): G \rightarrow G^{\prime}$ between depicted graphs $G$ and $G^{\prime}$ is the unique morphism satisfying $S \subseteq f(S)$ for all $S \in V_{G}$. For instance, for nodes $\{a\}$ and $\{b\}$ in the left hand side of $\rho$ (Example 1), $\rho(\{a\})=$ $\rho(\{b\})=\{a, b\}$ of the right hand side. We will use examples that ensure uniqueness of each $f$ (in particular, we ensure that the mapping of edges $\phi_{E}$ is uniquely determined by the mapping of nodes $\phi_{V}$ ). Colors are purely supplementary.
Definition 2 (Match). A match for a ToyPO rule $\rho: L \rightarrow R$ in a host graph $G$ is an injective morphism $m: L \rightharpoondown G$. The image $m(L) \subseteq G$ is an occurrence of $L$ in $G$.
Example 2. The injective morphism $m: L \hookrightarrow G$ depicted by

is a match for rule $\rho$ of Example 1 in the host graph $G$. Three other matches are possible: $d \rightarrow a, e \rightarrow f$ and $f \rightarrow e$.
Remark 1. We require injectivity of $m$ for three reasons. First, it is easier to understand. Second, it yields a strictly more expressive formalism (cf. Habel et al. [10]). Third, it better prepares for $\mathrm{PBPO}^{+}$, where matches are injective as well.

Given rule $\rho: L \rightarrow R$ and match $m: L \rightharpoondown G$ of Examples 1 and 2, respectively, arguably the most reasonable result of the rewrite step is the graph

$$
H=\text { (d) } \rightarrow a b
$$

because this graph can be understood as the minimal solution in which $m(L)$ is replaced by $R$ in $G$. More specifically, no elements of $G-m(L)$ are deleted, duplicated or identified; and no elements other than those in $R-\rho(L)$ are added. Astonishingly, this informal notion of a minimal solution can be defined formally and abstractly using the language of category theory; that is, without making any reference whatsoever to graphs or graph homomorphisms.
Definition 3 (Pushout [16, 2]). The pushout of a span $G \stackrel{m}{\leftarrow} L \stackrel{\rho}{\rightarrow} R$ is a cospan $\sigma=G \stackrel{i G}{\rightarrow} H \stackrel{i_{R}}{\leftarrow} R$ such that

1. $\sigma$ is a candidate solution: $i_{G} \circ m=i_{R} \circ \rho$; and
2. $\sigma$ is the minimal solution: for any cospan $G \stackrel{i_{G}^{\prime}}{\leftrightarrows} H^{\prime} \stackrel{i_{R}^{\prime}}{\leftarrow} R$ that satisfies $i_{G}{ }^{\prime} \circ m=i_{R}{ }^{\prime} \circ \rho$, there exists a unique morphism $x: H \rightarrow H^{\prime}$ such that $i_{G}{ }^{\prime}=x \circ i_{G}$ and $i_{R}{ }^{\prime}=x \circ i_{R}$.
Both requirements are conveniently visualized in the commuting diagram depicted in Figure 1.


Figure 1: Pushout.

Pushouts are unique up to isomorphism if they exist (and they always do in the category of graphs). A useful intuitive description of a pushout is that of a gluing construction, because $H$ can be thought of as the result of gluing $G$ and $R$ along shared interface $L$. This view is especially intuitive if $m$ is injective, which is always the case in our setting.
Exercise 1. For span $G \stackrel{m}{\longleftrightarrow} L \stackrel{\rho}{\rightarrow} R$ given by Examples 1 and 2, verify that

1. the following pushout is indeed a candidate solution (i.e., satisfies condition 1 of Definition 3):

2. the following graphs (with the obvious choices for the cospan morphisms $i_{G}, i_{R}$ ) constitute two other candidate solutions:

$$
H^{\prime}=(d) \rightarrow\left(\begin{array}{c}
a b \\
\frac{c e f}{c} \\
\Im
\end{array} \quad H^{\prime \prime}=(d) \rightarrow(a b) \text { (c) (b) } \leftrightarrows f\right.
$$

3. $H$ satisfies condition 2 of Definition 3 specifically for competing candidates $H^{\prime}$ and $H^{\prime \prime}$; and
4. $H^{\prime}$ and $H^{\prime \prime}$ both fail condition 2 of Definition 3 because
(a) no suitable witness $x: H^{\prime} \rightarrow H$ exists (the identification of elements cannot be undone); and
(b) a suitable witness $x: H^{\prime \prime} \rightarrow H$ does not exist uniquely (node $g$ can be mapped freely).

For a set theoretic description of the pushout, one may consult König et al. [12]. For this paper, however, it suffices if the reader understands the pushout intuitively as a gluing construction, and that it can be used for the specification of identification and addition of elements.

We may now define the notion of a ToyPO rewrite step.
Definition 4 (ToyPO Rewrite Step). A ToyPO rule $\rho: L \rightarrow R$ and match $m: L \longmapsto G$ induce a ToyPO rewrite step $G \Rightarrow{ }_{\mathrm{ToyPO}}^{\rho, m} H$ if there exists a pushout of the form shown on the right.


## 3 ToyPB

Next, we would like to specify the duplication and deletion of elements. This is slightly more challenging, and allows for a larger variety of solutions.

For some historical context, and to illustrate the solution space, consider the approach where we invert the procedure described in Section 2. For example, we read rule $\rho: L \rightarrow R$ of Example 1 right-to-left, suggestively writing the type signature as $\rho: R \leftarrow L$. Read in this way, $\rho$ intuitively specifies the duplication of node $a b$ and the deletion of node $c$. When we find a match $m: R \mapsto G$, we try to show that $G$ can be understood as the result of a suitable gluing. That is, we try to find morphisms $l_{1}: L \rightarrow H$ and $l_{2}: H \rightarrow G$ such that the diagram shown on the right is a pushout square. Morphisms $l_{1}$ and $l_{2}$ together constitute a pushout complement for $\rho$ and $m$.


Example 3. The pushout square of Diagram (1) in Exercise 1 can be read as an inverted application of $\rho$, by reading morphism $i_{R}$ as the match, the bottom right graph as the host graph, and the bottom left graph as the result graph.

The inverse approach has two particular caveats:

1. Existence of pushout complements: Consider a rule $\rho$ that deletes a node $a$, and a match $m$ as depicted on the right (the domain of $\rho$ is the empty graph). Even though all pushouts exist in the category of graphs, and even though we
 have found a match $m$, a pushout complement does not exist for this corner: the depicted edge can never be obtained through a gluing around an empty interface. The more general implication of this observation is that we are only able to delete nodes if they do not leave any edges "dangling" (called the gluing condition). This can be considered a pleasant safety feature, but also a limitation: perhaps we would prefer to simply delete any incident edges (as a general principle), or even be able to specify more fine-grained control on the level of the rule itself.

2 Uniqueness of pushout complements: More importantly, unlike pushouts, pushout complements need not be unique: the square on the right shows that two pushout complements exist, one of which does not model duplication (similarly, there exists another pushout complement for the pushout square of Diagram (1)). This
 is problematic if it is desired that rewrite step results are uniquely determined by the rule and match. In the category of graphs, uniqueness of pushout complements can at least be ensured by restricting rules $\rho$ to injective morphisms (thus allowing deletion, but not duplication of elements). However, in other categories, such as the category of simple graphs, this is not generally sufficient.
These two caveats notwithstanding, the most dominant graph rewriting method, called the Double Pushout (DPO) approach, combines the pushout complement approach (with the injectivity requirement) with the ToyPO approach. In doing so, it enables the specification of rewrite steps with deletion, identification and addition features, for matches $m$ that satisfy the gluing condition.

Definition 5 (DPO Rewriting [9]). A DPO rewrite rule $\rho$ is a span $L \stackrel{L}{\longleftrightarrow} K \xrightarrow{r} R$. A diagram depicted on the right defines a DPO rewrite step $G_{L} \Rightarrow{ }_{\mathrm{DPO}}^{\rho, m} G_{R}$, i.e., a step from $G_{L}$ to $G_{R}$ using rule $\rho$ and match $m: L \hookrightarrow G_{L}$.


Alternatives to the DPO approach avoid the construction of pushout complements. For instance, the Single Pushout (SPO) approach [13] relies on a single pushout construction, but uses partial graph homomorphisms instead of total morphisms, in order to specify deletion. In this approach, the gluing condition no longer needs to be checked either: all edges incident to a removed vertex are simply deleted. As another example, the Sesqui-Pushout (SqPO) approach [5] replaces the first PO square of DPO by what is called a final pullback complement square. This square allows duplication with deterministic behavior, and like SPO, deletes any edges that would be left dangling.

For our proposal, called ToyPB (short for ToyPullback), we consider a perspective that is dual to the ToyPO approach, rather than its inverse. First, instead of trying to find an occurrence of some pattern $L$ in a graph $G$ (through a match $m: L \hookrightarrow G$ ), we try to find a graph homomorphism $\alpha: G \rightarrow T$ into some graph $T$. When we adopt such a viewpoint, we will call $\alpha$ an adherence morphism, and we can think of $T$ as a kind of type graph. For instance, if $T$ is the graph from Figure 2 then any adherence $\alpha: G \rightarrow T$ assigns one of two


Figure 2: Node colors.

$$
T=G{ }^{x} ⿹
$$

Figure 3: Edge colors.
"colors" $a$ and $b$ to nodes of $G$ such that no two $G$-neighbors have the same color ( $\alpha$ is effectively a proof that $G$ is 2 -colorable or bipartite); and if $T$ is as in Figure 3 then we can regard any $\alpha$ as assigning every edge of $G$ one of two "colors", depending on which loop is being assigned. We now consider a ToyPB rule to specify a manipulation of such type graphs.

Definition 6 (ToyPB Rule). A ToyPB rule is a morphism $\rho: L^{\prime} \leftarrow R^{\prime} . L^{\prime}$ and $R^{\prime}$ are called type graphs.
Observe that ToyPO and ToyPB rules are formally identical. But it helps to emphasize the difference in perspective by presenting the definitions differently.
Example 4. Rule (a) $\leftrightarrows$ (b) $\stackrel{\rho}{\leftarrow}$ (a) $\rightarrow$ (b) specifies the deletion of edges that originate in $b$-nodes, and the duplication of edges that originate in $a$-nodes. An intended example application is given by the commutative square in Figure 4. In this and the next example, the rule lies at the bottom of the square, and the node identities of the rule have been adjusted to indicate how the morphisms are defined (see Notation 1).
Example 5. Let us again think of an adherence $\alpha: G \rightarrow T$ on graphs $G$ and $T$ as assigning colors to elements of $G$. Rule $G(a b) \leftrightarrows \leftarrow$ (a) $\rightarrow$ b specifies the deletion of all "red" edges, and splits all nodes so that the "blue" edges are rendered as edges of a (one-way) bipartite graph. An intended example application is given by the commutative square in Figure 5.

The desired outcomes of Examples 4 and 5 (which we hope the reader agrees are the most reasonable ones given the adopted intuitive perspective) can be obtained through a pullback construction, a notion that is the dual to the pushout (Definition 3). Like pushouts, pullbacks are unique up to isomorphism.
Definition 7 (Pullback [16, 2]). The pullback of a cospan $G \xrightarrow{\alpha} L^{\prime} \stackrel{\rho}{\leftarrow} R^{\prime}$ is a span $\sigma=G \stackrel{i_{G}}{\leftarrow} H \stackrel{i_{R}}{\longrightarrow} R$ such that

1. $\sigma$ is a candidate solution: $\alpha \circ i_{G}=\rho \circ i_{R}$; and
2. $\sigma$ is the minimal solution: for any span $G \stackrel{i_{G}{ }^{\prime}}{\leftarrow} H^{\prime} \xrightarrow{i_{R}{ }^{\prime}} R^{\prime}$ that satisfies $\alpha \circ i_{G}{ }^{\prime}=\rho \circ i_{R}{ }^{\prime}$, there exists a unique morphism $x: H^{\prime} \rightarrow H$ such that $i_{G}{ }^{\prime}=i_{G} \circ x$ and $i_{R}{ }^{\prime}=i_{R} \circ x$.

Both requirements are conveniently visualized in the commuting diagram


Figure 6: Pullback. in Figure 6.

Remark 2 (Fibered Product). The metaphor of a pushout as a gluing construction unfortunately does not dualize very well. However, in the category of sets, the pullback can be understood as fibered product, which is a generalization of the familiar Cartesian product: the pullback object $H$ (Figure 6) contains all pairs $(x, y)\left(x \in G\right.$ and $\left.y \in R^{\prime}\right)$ for which $\alpha(x)=\rho(y)$. For the category of graphs, the vertex set $V$ and edge set $E$ of $H$ can in fact be constructed by constructing the fibered products for $V$ and $E$ independently.


Figure 4: Example 4.


Figure 5: Example 5.

Exercise 2. Adapt Exercise 1 for pullbacks: construct some candidates that compete with the solutions given in Examples 4 and 5 (e.g., consider the empty graph), and assess why these candidates do not qualify as pullbacks.

We may now define the notion of a ToyPB rewrite step.
Definition 8 (ToyPB Rewrite Step). A ToyPB rule $\rho: L^{\prime} \leftarrow R^{\prime}$ and adherence morphism $\alpha: G \rightarrow L^{\prime}$ induce a ToyPB rewrite step $G \Rightarrow{ }_{\mathrm{ToyPB}}^{\rho, \alpha} H$ if there exists a pullback of the form depicted on the right.


Note that unlike ToyPO, ToyPB does not have any injectivity restrictions, because we would usually like arbitrarily large graphs $G$ to be typeable by a relatively small type graph $L^{\prime}$.

## 4 PBPO $^{+}$

The following preliminary exercise shows that we can use pullbacks to construct preimages. It is useful for understanding $\mathrm{PBPO}^{+}$rules and matches.
Exercise 3 (Computing Preimages). For cospans $L \stackrel{t_{L}}{\hookrightarrow} L^{\prime} \stackrel{l^{\prime}}{\leftarrow} K^{\prime}$ with one injective leg $t_{L}$, define $l^{\prime-1}\left(t_{L}\right)$ as the subgraph of $K^{\prime}$ that is mapped onto the subgraph $t_{L}(L)$ of $L^{\prime}$. Using intuitive reasoning, convince yourself that for a pullback, as depicted on the right, we have $K \cong l^{\prime-1}\left(t_{L}\right)$.


Definition 9 ( $\mathrm{PBPO}^{+}$Rewrite Rule [4, 14]). A $P B P O^{+}$rewrite rule $\rho$ is a collection of objects and morphisms, arranged as follows around a pullback square:
$L$ is the lhs pattern of the rule, $L^{\prime}$ its type graph, and $t_{L}$ the embedding of $L$ into $L^{\prime}$. Similarly for the interface $K . R$ is the rhs pattern or replacement for $L$.

Thus, a $\mathrm{PBPO}^{+}$rule uses a type graph $L^{\prime}$ with a distinguished pattern graph $L$, specified by means of an injection $t_{L}: L \hookrightarrow L^{\prime}$. A morphism $l^{\prime}: L^{\prime} \leftarrow K^{\prime}$ is used to specify deletion and duplication on the type graph, similar to a ToyPB rule. A morphism $r: K \rightarrow R$ is then used to specify identification and addition specifically on $l^{\prime-1}\left(t_{L}\right)$, similar to a ToyPO rule.

For matching, we would like to view $L^{\prime}$ as providing a type environment around the designated pattern $t_{L}(L) \subseteq L^{\prime}$. For rewrite steps, this means that precisely one occurrence of $L$ in $G$ should be mapped onto $t_{L}(L)$ by an adherence morphism $\alpha: G \rightarrow L^{\prime}$. Stated in terms of preimages, we require that $\alpha^{-1}\left(t_{L}\right) \cong L$. We call such a match a strong match.
Definition 10 (Strong Match [14]). An adherence morphism $\alpha: G \rightarrow L^{\prime}$ establishes a strong match for an embedding $t_{L}: L \hookrightarrow L^{\prime}$ if the square depicted on the right is a pullback square. The induced morphism $m: L \longmapsto G$ is called the match morphism.


Example 6. The left of



Figure 7: Example illustrating duplication, deletion and redirection and constraining application.
visualizes a strong match: $L^{\prime}$ has exactly one occurrence of $L$ (namely $m(L)$ ) mapped onto $t_{L}(L)$. The square is a pullback square. The right is merely a commutative square, not a pullback square: because all of $G$ is collapsed onto $t_{L}(L)$, the pullback object $\alpha^{-1}\left(t_{L}\right)$ is in fact $G$ itself.

The definition of a $\mathrm{PBPO}^{+}$rewrite step consists of a strong match square, a ToyPB-like pullback square (using "rule" $l^{\prime}: L^{\prime} \leftarrow K^{\prime}$ ), and a ToyPO-like pushout square (using "rule" $r: K \rightarrow R$ ). For this, the pullback and pushout squares need to be appropriately connected. As stated in the definition below, this can always be done, because the existence of a unique morphism $u: K \mapsto G_{K}$ satisfying $t_{K}=u^{\prime} \circ u$ is guaranteed.

Definition 11 ( $\mathrm{PBPO}^{+}$Rewrite Step [14]). A PBPO ${ }^{+}$rewrite rule $\rho$ (Definition 9), match morphism $m: L \hookrightarrow G_{L}$ and adherence morphism $\alpha: G_{L} \rightarrow L^{\prime}$ induce a rewrite step $G_{L} \Rightarrow_{\mathrm{PBPO}^{+}}^{\rho,(m, \alpha)} G_{R}$ if the properties indicated by the commuting diagram

hold, where $u: K \rightarrow G_{K}$ is the unique (and necessarily monic) morphism satisfying $t_{K}=u^{\prime} \circ u$ [14, Lemma 11]. ${ }^{1}$
Example 7 (Rewrite Step). The rewrite step $G_{L} \Rightarrow{ }_{\mathrm{PBPO}^{+}}^{\rho,(m, \alpha)} G_{R}$ depicted in Figure 7 illustrates some important features of $\mathrm{PBPO}^{+}$. The rule $\rho$ consists of the objects $L, K, R, L^{\prime}$ and $K^{\prime}$ together with the obvious morphisms. The pattern $L$ requires any host graph $G_{L}$ to contain three nodes, and two of these nodes have an edge targeting the third node. The graph $L^{\prime}$ describes the permitted shapes of the host graph

[^0]around the pattern $L$. Due to the strong match condition, any $\alpha: G_{L} \rightarrow L^{\prime}$ has to map all nodes and edges in the context $G_{L}-m(L)$ of the host graph nodes onto $L^{\prime}-t_{L}(L)$. So, in particular, $c_{1} c_{2}$ in $L^{\prime}$ captures all the context nodes of $G_{L}$. Each edge in $L^{\prime}-t_{L}(L)$ is a placeholder for an arbitrary number ( 0 or more) of edges in the host graph. This example illustrates the following features:
(i) Application conditions:

The graph $L^{\prime}$ allows for (an arbitrary number of) edges from $x_{1} x_{2}$ to the context, from the context to $z$, from $y_{1} y_{2}$ to $x_{1} x_{2}$ and from $y_{1} y_{2}$ to $z$ (and edges among context nodes). Besides the edges in the pattern, any other edges are forbidden. For instance there cannot be edges from $z$ to the context, and no additional edges from $x_{1} x_{2}$ to $y_{1} y_{2}$.
(ii) Duplicating and deleting elements:

The morphism $l^{\prime}: K^{\prime} \rightarrow L^{\prime}$ enables the duplication and deletion of nodes and edges. For instance, from $L^{\prime}$ to $K^{\prime}$, the node $x_{1} x_{2}$ is duplicated along with its edges to the context (indicated in red). The edges from $c_{2}$ to $x$ (indicated in blue) and the thick edges are deleted, because they do not lie in the image of $l^{\prime}$.
(iii) Identifying and adding elements:

The morphism $r: K \rightarrow R$ enables the identification of elements of $K$, and the addition of new elements. Here, $K$ is the result of restricting the duplication and deletion effects of $l^{\prime}$ to $t_{L}(L) \cong L$. In the example, $r$ identifies (or merges) $x_{1}$ with $z$ and $x_{2}$ with $y_{2}$, adds a fresh node $u$ and a fresh edge from $x_{2} y_{2}$ to itself. In the middle row, observe that the sources and targets of edges are updated accordingly from $G_{K}$ to $G_{R}$. For instance, the edges $y_{1} \rightarrow x_{1}$ and $y_{2} \rightarrow z$ in $G_{K}$ are redirected to target the merged node $x_{1} z$ in $G_{R}$.
(iv) Edge redirection:

The combination of duplication along $l^{\prime}: K^{\prime} \rightarrow L^{\prime}$ and merging along $r: K \rightarrow R$ enables the arbitrary redirection of all those endpoints (source and target) of edges that lie in the pattern $m(L)$. Importantly, the edge itself does not need to be part of the pattern, only the endpoint to be redirected. For instance, the edges from $y_{1} y_{2}$ to $z$ (indicated in green) are redirected to go from $x_{2}$ to $x_{1}$. This is achieved by first duplicating one endpoint of the edge, namely the source $y_{1} y_{2}$, and then merging the fresh source $y_{2}$ with $x_{2}$, and the target $z$ with $x_{1}$.

For another example, see [15, Example 15].

## 5 Related Work

One of the first tutorials by Ehrig et al. [8] present intuitive approaches to DPO and SPO, also covering some metatheoretic properties. Baresi et al. [1] take a different approach and provide a broad and applied introduction to the graph transformation research field, introducing DPO set theoretically. The tutorial by Heckel [11] discusses a notion of typed graph transformation informally. The problem of dangling edges is highlighted, and some solutions that have been proposed to deal with them are discussed. The very recent tutorial by König et al. [12] explains the "essence" of DPO, and gives a gentle build-up towards pushouts. In their case, this involves giving a set-theoretic definition of pushouts. Only SPO is mentioned when the subject of deletion in unknown contexts is discussed. In addition, the tutorial discusses attributed graph rewriting and tools.

For a more extensive overview of tutorials, see [12, Section 7.1].

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[^0]:    ${ }^{1}$ Morphism $u$ can be obtained by pulling back $m$ along $g_{L}$. However, as shown in the cited lemma, the solution for $u$ in $t_{K}=u^{\prime} \circ u$ exists and is uniquely determined for $\mathrm{PBPO}^{+}$(it is not for PBPO [14, Remark 17]). We thus need not specify how $u$ is constructed, allowing us to simplify the diagram.

