

Parallel Independence in Attributed Graph Rewriting

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We use graphs where vertices and arrows are attributed with *sets* of values, and rules that allow to delete data from a graph, to create new vertices or arrows, and to include values in attributes. Rules may be applied simultaneously, yielding a notion of parallelism that generalizes cellular automata in particular by allowing infinite matchings of rules in a graph. This is first used to define a notion of *sequential independence* of a set M of matchings of rules, even when M is infinite. Next, a notion of *parallel independence* of matchings is defined that accounts for the particular treatment of attributes, and it is proven to characterize sequential independence. Last, the *effective deletion property*, a condition that ensures that rules can be applied in parallel without conflicts, is proven to generalize parallel independence.

1 Introduction

The notion of parallel independence has been studied mostly in the algebraic approach to graph rewriting, see [1] and the references therein. It basically consists in a condition on concurrent transformations of an object that characterizes the possibility to apply the transformations sequentially in any order such that all such sequences of transformations yield the same result. When two transformations are involved this takes the form of the diamond property and is known as the *Local Church-Rosser Problem*. Parallel independence then allows to define critical pairs, a central notion in Term and Graph Rewriting.

This problem should therefore also be considered in algorithmic approaches to graph rewriting. Indeed, the informal description of parallel independence given above makes perfect sense out of the algebraic approach; it is purely operational. Consider for instance Python's multiple assignment $a, b := b, a$ that swaps the values of a and b . We naturally understand this as a parallel expression $a := b \parallel b := a$. If a and b have the same value then the two assignments can be evaluated in sequence in any order; they are *parallel independent*. If however they have distinct values, the two sequential evaluations yield different results (and none corresponds to the intended meaning); the two assignments are *parallel dependent*. Parallel dependence typically occurs in cellular automata when the local rule is applied to neighbor cells (because of the overlap); thus sequential applications of the local rule would result in non deterministic automata. It is therefore necessary to define a parallel transformation that handles parallel dependence. One has been described in [6], where graphs are attributed by *sets* of values (see Sections 2 and 3). Sets are convenient because they allow to add as many values as required, just as new vertices and arrows can always be added (see Section 6 for a more precise argument).

But there is a fundamental difference between the two, that lies in the semantics of the rules described in Section 3: vertices and arrows are always added as *new* objects, but values are added by inclusion in attributes, where they may not be new. This is different from E-graphs, an alternate notion of attributed graphs with any number of values (see [3]), and is bound to have an impact on parallel independence.

We are first faced with the same difficulty as in the algebraic approach, that is to apply transformations meant for the same graph *in sequence*, hence on already transformed graphs (except for the one considered first). This is solved in Section 4 by taking advantage of the parallel transformation defined

in Section 3. In Section 5 a definition of parallel independence adapted to the present framework is given, and proven to be correct since it is equivalent to sequential independence. Finally, Section 6 is devoted to the *effective deletion property* from [6], a condition that guarantees that parallel rules do not clash. It is proved that parallel independence entails effective deletion, hence that the latter tolerates more overlaps than the former. The proofs can be found in [4].

2 Attributed Graphs

We assume a many-sorted signature Σ and a set \mathcal{V} of *variables*, disjoint from Σ , such that every variable has a Σ -sort. For any finite $X \subseteq \mathcal{V}$, $\mathcal{T}(\Sigma, X)$ denotes the algebra of Σ -terms over X .

An *attributed graph* (or *graph* for short) G is a tuple $(\dot{G}, \vec{G}, \hat{G}, \check{G}, \mathcal{A}_G, \mathring{G})$ where \dot{G}, \vec{G} are sets, \hat{G}, \check{G} are the *source* and *target* functions from \vec{G} to \dot{G} , \mathcal{A}_G is a Σ -algebra and \mathring{G} is an *attribution* of G , i.e., a function from $\dot{G} \cup \vec{G}$ to $\mathcal{P}(\lfloor \mathcal{A}_G \rfloor)$ (the carrier set $\lfloor \mathcal{A}_G \rfloor$ of \mathcal{A}_G is the disjoint union of the carrier sets of the sorts in \mathcal{A}_G). We assume that \dot{G}, \vec{G} and $\lfloor \mathcal{A}_G \rfloor$ are pairwise disjoint; their elements are respectively called *vertices*, *arrows* and *attributes*. G is *unlabelled* if $\mathring{G}(x) = \emptyset$ for all $x \in \dot{G} \cup \vec{G}$, it is *finite* if the sets \dot{G}, \vec{G} and $\mathring{G}(x)$ are finite. The *carrier* of G is the set $\lfloor G \rfloor \stackrel{\text{def}}{=} \dot{G} \cup \vec{G} \cup \lfloor \mathcal{A}_G \rfloor$.

A graph H is a *subgraph* of G , written $H \triangleleft G$, if the *underlying graph* $(\dot{H}, \vec{H}, \hat{H}, \check{H})$ of H is a subgraph of G 's underlying graph (in the usual sense), $\mathcal{A}_H = \mathcal{A}_G$ and $\mathring{H}(x) \subseteq \mathring{G}(x)$ for all $x \in \dot{H} \cup \vec{H}$.

A *morphism* α from graph H to graph G is a function from $\lfloor H \rfloor$ to $\lfloor G \rfloor$ such that the restriction of α to $\dot{H} \cup \vec{H}$ is a morphism from H 's to G 's underlying graphs (that is, $\hat{G} \circ \alpha = \alpha \circ \hat{H}$ and $\check{G} \circ \alpha = \alpha \circ \check{H}$, this restriction of α is called the *underlying graph morphism* of α), the restriction of α to $\lfloor \mathcal{A}_H \rfloor$ is a Σ -homomorphism from \mathcal{A}_H to \mathcal{A}_G , denoted $\hat{\alpha}$, and $\hat{\alpha} \circ \mathring{H}(x) \subseteq \mathring{G} \circ \alpha(x)$ for all $x \in \dot{H} \cup \vec{H}$. Note that $H \triangleleft G$ iff $\lfloor H \rfloor \subseteq \lfloor G \rfloor$ and the canonical injection from $\lfloor H \rfloor$ to $\lfloor G \rfloor$ is a morphism from H to G . A morphism α is a *matching* if the underlying graph morphism of α is injective. α is an *isomorphism* if α and α^{-1} are bijective morphisms, hence iff the underlying graph morphism of α is an isomorphism, $\hat{\alpha}$ is a Σ -isomorphism and $\hat{\alpha} \circ \mathring{H} = \mathring{G} \circ \alpha$. For all $F \triangleleft H$, the *image* $\alpha(F)$ is the smallest subgraph of G w.r.t. the order \triangleleft such that $\alpha|_{\lfloor F \rfloor}$ is a morphism from F to $\alpha(F)$.

Given two attributions l and l' of G let $l \setminus l'$ (resp. $l \cap l', l \cup l'$) be the attribution of G that maps any x to $l(x) \setminus l'(x)$ (resp. $l(x) \cap l'(x), l(x) \cup l'(x)$). If l is an attribution of a subgraph $H \triangleleft G$, it is implicitly extended to the attribution of G that is identical to l on $\dot{H} \cup \vec{H}$ and maps any other entry to \emptyset .

Unions of graphs can only be formed between *joinable* graphs, i.e., graphs that have a common part. We start with a simpler notion of joinable functions.

Definition 2.1 (joinable functions). Two functions $f : D \rightarrow C$ and $g : D' \rightarrow C'$ are *joinable* if $f(x) = g(x)$ for all $x \in D \cap D'$. Then, the *meet* of f and g is the function $f \wedge g : D \cap D' \rightarrow C \cap C'$ that is the restriction of f (or g) to $D \cap D'$. The *join* $f \vee g$ is the unique function from $D \cup D'$ to $C \cup C'$ such that $f = (f \vee g)|_D$ and $g = (f \vee g)|_{D'}$.

For any set I and any I -indexed family $(f_i : D_i \rightarrow C_i)_{i \in I}$ of pairwise joinable functions, let $\vee_{i \in I} f_i$ be the only function from $\bigcup_{i \in I} D_i$ to $\bigcup_{i \in I} C_i$ such that $f_i = (\vee_{i \in I} f_i)|_{D_i}$ for all $i \in I$.

We see that any two restrictions $f|_A$ and $f|_B$ of the same function f are joinable, and then $f|_A \wedge f|_B = f|_{A \cap B}$ and $f|_A \vee f|_B = f|_{A \cup B}$. Conversely, if f and g are joinable then each is a restriction of $f \vee g$.

Definition 2.2 (joinable graphs). Two graphs H and G are *joinable* if $\mathcal{A}_H = \mathcal{A}_G$, $\dot{H} \cap \vec{G} = \vec{H} \cap \dot{G} = \emptyset$, and the functions \hat{H} and \hat{G} (and similarly \check{H} and \check{G}) are joinable. We can then define the graphs

$$\begin{aligned} H \sqcap G &\stackrel{\text{def}}{=} (\dot{H} \cap \dot{G}, \vec{H} \cap \vec{G}, \hat{H} \wedge \hat{G}, \check{H} \wedge \check{G}, \mathcal{A}_H, \mathring{H} \cap \mathring{G}), \\ H \sqcup G &\stackrel{\text{def}}{=} (\dot{H} \cup \dot{G}, \vec{H} \cup \vec{G}, \hat{H} \vee \hat{G}, \check{H} \vee \check{G}, \mathcal{A}_H, \mathring{H} \cup \mathring{G}). \end{aligned}$$

Similarly, if $(G_i)_{i \in I}$ is an I -indexed family of graphs that are pairwise joinable, and \mathcal{A} is an algebra such that $\mathcal{A} = \mathcal{A}_{G_i}$ for all $i \in I$, then let $\bigsqcup_{i \in I} G_i \stackrel{\text{def}}{=} (\bigcup_{i \in I} \dot{G}_i, \bigcup_{i \in I} \vec{G}_i, \gamma_{i \in I} \dot{G}_i, \gamma_{i \in I} \vec{G}_i, \mathcal{A}, \bigcup_{i \in I} \dot{G}_i)$.

It is easy to see that these structures are graphs: the sets of vertices and arrows are disjoint and the adjacency functions have the correct domains and codomains. If $I = \emptyset$ the chosen algebra \mathcal{A} is generally obvious from the context. We see that any two subgraphs of G are joinable, and that $H \triangleleft G$ iff $H \sqcap G = H$ iff $H \sqcup G = G$. These operations are commutative and, on triples of pairwise joinable graphs, they are associative and distributive over each other.

For any sets V, A and attribution l , we say that G is *disjoint from* V, A, l if $\dot{G} \cap V = \emptyset$, $\vec{G} \cap A = \emptyset$ and $\dot{G}(x) \cap l(x) = \emptyset$ for all $x \in \dot{G} \cup \vec{G}$. We write $G \setminus [V, A, l]$ for the largest subgraph of G (w.r.t. \triangleleft) that is disjoint from V, A, l . This provides a natural way of removing objects from an attributed graph. It is easy to see that this subgraph always exists (it is the union of all subgraphs of G disjoint from V, A, l), hence rewriting steps will not be restricted by a *gluing condition* as in the Double-Pushout approach (see [3]).

3 Applying Rules in Parallel

Definition 3.1 (rules, matchings). For any finite $X \subseteq \mathcal{V}$, a (Σ, X) -graph is a finite graph G such that $\mathcal{A}_G = \mathcal{T}(\Sigma, X)$. Let $\text{Var}(G) \stackrel{\text{def}}{=} \bigcup_{x \in \dot{G} \cup \vec{G}} (\bigcup_{t \in \dot{G}(x)} \text{Var}(t))$, where $\text{Var}(t)$ is the set of variables occurring in t .

A *rule* r is a triple (L, K, R) of (Σ, X) -graphs such that L and R are joinable, $L \sqcap R \triangleleft K \triangleleft L$ and $\text{Var}(L) = X$ (see Remark 3.2 below).

A *matching* μ of r in a graph G is a matching from L to G such that $\hat{\mu}(\dot{L}(x) \setminus \dot{K}(x)) \cap \hat{\mu}(\dot{K}(x)) = \emptyset$ (or equivalently $\hat{\mu}(\dot{L}(x) \setminus \dot{K}(x)) = \hat{\mu}(\dot{L}(x)) \setminus \hat{\mu}(\dot{K}(x))$) for all $x \in \dot{K} \cup \vec{K}$. We denote $\mathcal{M}(r, G)$ the set of all matchings of r in G (they all have domain $[L]$).

We consider finite sets \mathcal{R} of rules such that for all $r, r' \in \mathcal{R}$, if $(L, K, R) = r \neq r' = (L', K', R')$ then $[L] \neq [L']$, so that $\mathcal{M}(r, G) \cap \mathcal{M}(r', G) = \emptyset$ for any graph G ; we then write $\mathcal{M}(\mathcal{R}, G)$ for $\bigsqcup_{r \in \mathcal{R}} \mathcal{M}(r, G)$. For any $\mu \in \mathcal{M}(\mathcal{R}, G)$ there is a unique rule $r_\mu \in \mathcal{R}$ such that $\mu \in \mathcal{M}(r_\mu, G)$, and its components are denoted $r_\mu = (L_\mu, K_\mu, R_\mu)$.

Remark 3.2. If X were allowed to contain a variable v not occurring in L , then v would freely match any element of \mathcal{A}_G and the set $\mathcal{M}(r, G)$ would contain as many matchings with essentially the same effect. Also note that $\text{Var}(R) \subseteq \text{Var}(L)$, R and K are joinable and $R \sqcap K = L \sqcap R$. The fact that K is not required to be a subgraph of R allows the possible deletion by other rules of data matched by K but not by R . This feature enables a straightforward representation of cellular automata (see [5]).

A rewrite step may involve the creation of new vertices in a graph, corresponding to the vertices of a rule that have no match in the input graph, i.e., those in $\dot{R} \setminus \dot{L}$ (or similarly may create new arrows). These vertices should really be new, not only different from the vertices of the original graph but also different from the vertices created by other transformations (corresponding to other matchings in the graph). This is computationally easy to do but not that easy to formalize in an abstract way. We simply reuse the vertices x from $\dot{R} \setminus \dot{L}$ by *indexing* them with any relevant matching μ , each time yielding a new vertex (x, μ) which is obviously different from any new vertex (x, ν) for any other matching $\nu \neq \mu$, and also from any vertex of G .

Definition 3.3 (graph G_μ^\uparrow and matching μ^\uparrow). For any rule $r = (L, K, R)$, graph G and $\mu \in \mathcal{M}(r, G)$ we define a graph G_μ^\uparrow together with a matching μ^\uparrow of R in G_μ^\uparrow . We first define the sets

$$G_\mu^\uparrow \stackrel{\text{def}}{=} \mu(\dot{R} \cap \dot{K}) \uplus ((\dot{R} \setminus \dot{K}) \times \{\mu\}) \quad \text{and} \quad \vec{G}_\mu^\uparrow \stackrel{\text{def}}{=} \mu(\vec{R} \cap \vec{K}) \uplus ((\vec{R} \setminus \vec{K}) \times \{\mu\}).$$

Next we define $\mu\uparrow$ by: $\dot{\mu}\uparrow \stackrel{\text{def}}{=} \dot{\mu}$ and for all $x \in \dot{R} \cup \vec{R}$, if $x \in \dot{K} \cup \vec{K}$ then $\mu\uparrow(x) \stackrel{\text{def}}{=} \mu(x)$ else $\mu\uparrow(x) \stackrel{\text{def}}{=} (x, \mu)$. Since the restriction of $\mu\uparrow$ to $\dot{R} \cup \vec{R}$ is bijective, then $\mu\uparrow$ is a matching from R to the graph

$$G_\mu^\uparrow \stackrel{\text{def}}{=} (\dot{G}_\mu^\uparrow, \vec{G}_\mu^\uparrow, \mu\uparrow \circ \dot{R} \circ \mu\uparrow^{-1}, \mu\uparrow \circ \vec{R} \circ \mu\uparrow^{-1}, \mathcal{A}_G, \dot{\mu}\uparrow \circ \dot{R} \circ \mu\uparrow^{-1}).$$

By construction $\mu\uparrow(R) = G_\mu^\uparrow$, μ and $\mu\uparrow$ are joinable and $\mu \wedge \mu\uparrow$ is a matching from $R \sqcap K$ to $\mu(R \sqcap K)$. It is easy to see that the graph G and the graphs G_μ^\uparrow are pairwise joinable.

For any set $M \subseteq \mathcal{M}(\mathcal{R}, G)$ of matchings in a graph G we define below how to transform G by applying simultaneously the rules associated with matches in M .

Definition 3.4 (graph $G\|_M$). For any graph G , set $M \subseteq \mathcal{M}(\mathcal{R}, G)$ and matching $\mu \in \mathcal{M}(\mathcal{R}, G)$, let

$$G\|_M \stackrel{\text{def}}{=} G \setminus [V_M, A_M, \ell_M] \sqcup \bigsqcup_{\mu \in M} G_\mu^\uparrow \text{ where}$$

$$V_M \stackrel{\text{def}}{=} \bigcup_{\mu \in M} \mu(\dot{L}_\mu \setminus \dot{K}_\mu), \quad A_M \stackrel{\text{def}}{=} \bigcup_{\mu \in M} \mu(\vec{L}_\mu \setminus \vec{K}_\mu) \text{ and } \ell_M \stackrel{\text{def}}{=} \bigcup_{\mu \in M} \dot{\mu} \circ (\dot{L}_\mu \setminus \dot{K}_\mu) \circ \mu^{-1}.$$

If M is a singleton $\{\mu\}$ we write $G\|_\mu$ for $G\|_M$, V_μ for V_M , etc.

$G\|_M$ is guaranteed to be a graph since the \sqcup operation is only applied on joinable graphs. Every morphism $\mu\uparrow$ is a matching from the right hand side R_μ to the result $G\|_M$ of the transformation. The case where M is a singleton defines the classical semantics of one sequential rewrite step.

Definition 3.5 (sequential rewriting). For any finite set of rules \mathcal{R} , we define the relation $\rightarrow_{\mathcal{R}}$ of *sequential rewriting* by stating that, for all graphs G and H ,

$$G \rightarrow_{\mathcal{R}} H \text{ iff there exists some } \mu \in \mathcal{M}(\mathcal{R}, G) \text{ such that } H \simeq G\|_\mu.$$

4 Sequential Independence

In the Double-Pushout approach to graph rewriting (see [3]), sequential independence is a property of two consecutive direct transformations, formulated as the existence of two commuting morphisms j_1 and j_2 as shown below.

$$\begin{array}{ccccccc}
 L_1 & \longleftarrow & K_1 & \longrightarrow & R_1 & & L_2 \longleftarrow K_2 \longrightarrow R_2 \\
 \downarrow \mu_1 & & \downarrow & & \swarrow \mu_2 & \searrow \mu_1 & \downarrow \\
 G & \longleftarrow & D_1 & \longrightarrow & H_1 & \longleftarrow & D_2 \longrightarrow H_2
 \end{array}$$

$\swarrow j_2 \quad \searrow j_1$

It is then proven by the Local Church-Rosser Theorem that the two production rules can be applied in reverse order to G and yield the same result H_2 (we may call this the *swapping property*). Of course, the matchings μ_1 and μ_2 are then replaced by other matchings that are related to μ_1 and μ_2 . A drawback of this definition is that it does not account for longer sequences of direct transformations. Indeed, if three consecutive steps are given by (μ_1, μ_2, μ_3) , it is possible to swap μ_1 with μ_2 if they are sequential independent, and similarly for μ_2 and μ_3 , but this does not imply that μ_1 and μ_3 can be swapped under these hypotheses (because the matchings, and hence the direct transformations, are modified by the swapping operations). We would need to express sequential independence between μ_1 and μ_3 , but the

definition does not apply since they are not consecutive steps. More elaborate notions of equivalence between sequences of direct transformations are thus required (see [2]).

Because of the specificities of our framework (no pushouts, horizontal morphisms are only canonical injections, and we do not have such a morphism from K to R) we need a different definition of sequential independence. It is natural to think of the swapping property as the definition, since it describes the operational meaning of parallel independence, but we are faced with another problem. We are dealing with possibly infinite sets of matchings of rules in a graph, and we cannot form a notion of infinite sequences of rewrite steps (because each step may both remove and add data). Yet we do not wish to restrict the notion to finite sets, not simply for the sake of generality but also because it is closely related to parallel independence, a notion that can naturally be defined on infinite sets (see below).

We may however use Definition 3.4 to handle infinite sets of matchings, and thus express sequential independence as the possibility to apply any rule *after* the others (and these can be applied in parallel), yielding the same result as a parallel transformation with the whole set of matchings. Yet this definition would not imply that subsets of a sequential independent set are sequential independent, hence it needs to be stated for all subsets.

Definition 4.1. For any graph G and set $M \subseteq \mathcal{M}(\mathcal{R}, G)$, we say that M is *sequential independent* if for all $M' \subseteq M$ and all $\mu \in M \setminus M'$,

- $\mu(L_\mu) \triangleleft G\|_{M'}$, hence there is a canonical injection j from $\mu(L_\mu)$ to $G\|_{M'}$,
- there exists an isomorphism α such that $\alpha(G\|_{M' \cup \{\mu\}}) = (G\|_{M'})\|_{j \circ \mu}$ and α is the identity on G .

The isomorphism α in Definition 4.1 is necessary to account for the difference between the isomorphic graphs $\mu \uparrow (R_\mu)$ and $(j \circ \mu) \uparrow (R_\mu)$.

It is then easy to see (by induction on the cardinality of M) that

Proposition 4.2. For any graph G and finite set $M \subseteq \mathcal{M}(\mathcal{R}, G)$, if M is sequential independent then

$$G \xrightarrow{\star_{\mathcal{R}}} G\|_M.$$

Of course there is usually more than one sequence of rewriting steps from G to $G\|_M$, since under the hypothesis they can be swapped; but without it there is generally none (as illustrated in Section 1). And the fact that there is one such sequence does not imply sequential independence, i.e., the converse of Proposition 4.2 is obviously not true.

5 Parallel Independence

In the Double-Pushout approach, parallel independence is a property of two direct transformations of the same object G , formulated as the existence of two commuting morphisms j_1 and j_2 as shown below.

$$\begin{array}{ccccccc}
 R_1 & \longleftarrow & K_1 & \longrightarrow & L_1 & & L_2 & \longleftarrow & K_2 & \longrightarrow & R_2 \\
 \downarrow & & \downarrow \\
 H_1 & \longleftarrow & D_1 & \longrightarrow & G & \longleftarrow & D_2 & \longrightarrow & H_2 & &
 \end{array}$$

$\begin{array}{ccc}
 & \swarrow & \searrow \\
 & j_2 & j_1 \\
 & \mu_1 & \mu_2 \\
 & \downarrow & \downarrow \\
 & G & G
 \end{array}$

This definition can easily be lifted to sets of matchings (or direct transformations) by considering all possible pairs of matchings, with a slight caveat. In this definition the two direct transformations may be identical, thus stating a property of a single transformation that is clearly not shared by all. But

Definition 3.4 does not allow to apply any member μ of M more than once (because applying μ any number of times in parallel would jeopardize determinism). For this reason any singleton M shall be considered as parallel independent.

The Local Church-Rosser Theorem mentioned above actually shows that μ_1 and μ_2 are parallel independent iff they correspond to a sequential independent pair (μ_1, μ'_2) , where μ_2 and μ'_2 are related. It is the symmetry between μ_1 and μ_2 that entails the swapping property. This is remarkable since parallel independence does not refer to the *results* of the direct transformations involved.

Our goal is therefore to formulate parallel independence in the present framework, in order to obtain an equivalence similar to the Local Church-Rosser Theorem. Considering that the pushout complement D_1 is replaced by the graph $G \setminus [V_{\mu_1}, A_{\mu_1}, \ell_{\mu_1}]$, the commuting property of j_2 amounts to $\mu_2(L_2) \triangleleft G \setminus [V_{\mu_1}, A_{\mu_1}, \ell_{\mu_1}]$, that can be more elegantly expressed as $\mu_2(L_2) \sqcap \mu_1(L_1) \triangleleft \mu_1(K_1)$. This simply means that any graph item that is matched twice cannot be removed.

However, our treatment of attributes makes it possible to recover in the right hand side an attribute that has been deleted in the left hand side (this is of course not possible for vertices or arrows). This possibility should therefore be accounted for in the notion of parallel independence, i.e., an attribute that is matched twice may be deleted provided it is recovered. We also need to consider what it means for an attribute to be matched: it may be the case that an (occurrence of an) attribute is matched by $v\uparrow$ but not by v (i.e., it corresponds to an occurrence of a term in the right hand side of a rule but to none in the left hand side). This leads to the following definition.

Definition 5.1. For any graph G and set $M \subseteq \mathcal{M}(\mathcal{R}, G)$, we say that M is *parallel independent* if

$$\mu(L_\mu) \sqcap (v(L_v) \sqcup v\uparrow(R_v)) \triangleleft \mu(K_\mu) \sqcup \mu\uparrow(R_\mu) \text{ for all } \mu, v \in M \text{ such that } \mu \neq v.$$

This definition may seem strange, but it is easy to see that on unlabelled graphs it amounts to $v(L_v) \sqcap \mu(L_\mu) \triangleleft \mu(K_\mu)$ for all $\mu \neq v$, i.e., to the standard algebraic notion of parallel independence (translated to the present framework). But the best justification for the definition is the following result.

Theorem 5.2. For any graph G and set $M \subseteq \mathcal{M}(\mathcal{R}, G)$, M is *parallel independent* iff M is *sequential independent*.

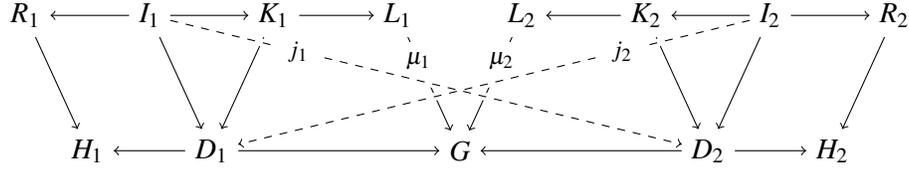
Thus Definition 5.1 arises as a characterization of sequential independence that does not refer to the results of the transformations, and indeed that does not rely on Definition 3.4, though of course it does rely on Definitions 2.2, 3.1 and 3.3. Note also that Definition 5.1 depends explicitly on right hand sides of rules, in contrast with the general algebraic definition of parallel independence given above, or with the Essential Condition of parallel independence in [1].

6 The Effective Deletion Property

We have not yet defined a relation of parallel rewriting as we did for sequential rewriting (Definition 3.5). The reason is that two matchings may conflict as one retains (in $R \sqcap K$) what another removes. The transformation offered by Definition 3.4 performs deletions before unions, which means that these conflicts are resolved by giving priority to retainers over removers. But if the deletion actions of a rule are not executed in a parallel transformation, how can we claim that this rule has been executed (or applied) in parallel with others? Thus, in order to define parallel rewriting with a clear semantics we need to rule out such conflicts.

One possibility is to translate to the present framework the notion of *parallel coherence* that has been devised in order to define algebraic parallel graph transformation (see [5]). This is a property of two

direct transformations of the same object G , formulated as the existence of two commuting morphisms j_1 and j_2 as shown below.



This notion clearly generalizes algebraic parallel independence. In the present framework the object I_2 is replaced by the graph $K_2 \sqcap R_2$, hence the commuting property of j_2 amounts to $\mu_2(K_2 \sqcap R_2) \triangleleft G \setminus [\mathbb{V}_{\mu_1}, \mathbb{A}_{\mu_1}, \ell_{\mu_1}]$, that can be expressed as $\mu_2(K_2 \sqcap R_2) \sqcap \mu_1(L_1) \triangleleft \mu_1(K_1)$. This simply means that any graph item that is matched by some $K \sqcap R$ cannot be removed by any rule.

Definition 6.1. For any graph G and set $M \subseteq \mathcal{M}(\mathcal{R}, G)$, we say that M is *parallel coherent* if

$$\mu(L_\mu) \sqcap \nu(K_\nu \sqcap R_\nu) \triangleleft \mu(K_\mu) \text{ for all } \mu, \nu \in M.$$

The problem here as above is that deleted attributes can be recovered by the right hand side of rules, and that this possibility is not accounted for in the algebraic definitions, since these do not distinguish between graph items and attributes. This leads to the following definition (see [6]).

Definition 6.2 (effective deletion property, full parallel rewriting). For any graph G , a set $M \subseteq \mathcal{M}(\mathcal{R}, G)$ is said to satisfy the *effective deletion property* if $G \parallel_M$ is disjoint from $\mathbb{V}_M, \mathbb{A}_M, \ell_M \setminus \ell_M^\uparrow$, where

$$\ell_M^\uparrow \stackrel{\text{def}}{=} \bigcup_{\mu \in M} \dot{\mu} \circ (\dot{R}_\mu \setminus \dot{K}_\mu) \circ \mu^{-1}.$$

For any finite set of rules \mathcal{R} , we define the relation $\Rightarrow_{\mathcal{R}}$ of *full parallel rewriting* by stating that, for all graphs G and H ,

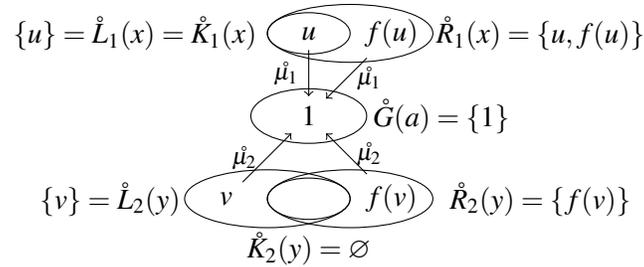
$$G \Rightarrow_{\mathcal{R}} H \text{ iff } \mathcal{M}(\mathcal{R}, G) \text{ has the effective deletion property and } H \simeq G \parallel_{\mathcal{M}(\mathcal{R}, G)}.$$

It can be shown that $\Rightarrow_{\mathcal{R}}$ is deterministic up to isomorphism, that is, if $G \Rightarrow_{\mathcal{R}} H$, $G' \Rightarrow_{\mathcal{R}} H'$ and $G \simeq G'$ then $H \simeq H'$. In particular, it is possible to represent any cellular automaton by a suitable rule r and a class of graphs that correspond to configurations of the automaton (every vertex corresponds to a cell), such that \Rightarrow_r (restricted to such graphs) is the transition function of the automaton.

This representation of cellular automata satisfies the effective deletion property, but it also satisfies parallel coherence. Hence Definition 6.2 may appear as a weird choice. One motivation behind the present work is to support this definition.

Our first argument in favor of Definition 6.2 is that parallel coherence is not sufficient because it does not generalize parallel independence, as shown by the following example.

Example 6.3. Let us consider rules $r_1 = (L_1, K_1, R_1)$ and $r_2 = (L_2, K_2, R_2)$ where the graphs L_1, K_1 and R_1 have only one vertex x , the graphs L_2, K_2 and R_2 have only one vertex y , and the attributes are as pictured below (u, v are variables and f is a unary function symbol). Let \mathcal{A}_G be the algebra with carrier set $\{1\}$ where f is interpreted as the constant function 1, and let G be the graph that has a unique vertex a with attribute $\{1\}$.



There are exactly two matchings of $\{r_1, r_2\}$ in G : μ_1 and μ_2 defined by $\mu_1(x) = a$, $\hat{\mu}_1(u) = 1$, $\mu_2(y) = a$ and $\hat{\mu}_2(v) = 1$. Let $M = \{\mu_1, \mu_2\}$, we see that M is not parallel coherent since $\mu_1(R_1 \sqcap K_1) \sqcap \mu_2(L_2) = G$ is not a subgraph of $\mu_2(K_2)$. However, we see that M is sequential independent since the matchings can be applied sequentially in any order, yielding the same graph G .

Our second argument is that the effective deletion property is sufficient because it does generalize both parallel coherence and parallel independence.

Theorem 6.4. *For any graph G and set $M \subseteq \mathcal{M}(\mathcal{R}, G)$ if M is parallel independent or parallel coherent then M has the effective deletion property.*

Hence effective deletion encompasses both a general algebraic notion translated to the present (non algebraic) framework, and a notion specific to this framework but that relies on an objective fact, that is Theorem 5.2. This does not mean that no other property is possible (especially a less general one) and that Definition 6.2 cannot be questioned. It is still a matter of choice, but there is evidence that this is a reasonable one. Another important feature is that if M does not have the effective deletion property, we see that there must be a conflict involving an element of V_M , A_M or ℓ_M . Hence the right hand sides of rules never create conflicts; this is due to the choice of attributes as sets of values.

We also see that

Corollary 6.5. *If $\mathcal{M}(\mathcal{R}, G)$ is finite and parallel independent then $G \rightarrow_{\mathcal{R}}^* G \parallel_M$ and $G \rightrightarrows_{\mathcal{R}} G \parallel_M$.*

Hence in this case $\rightrightarrows_{\mathcal{R}}$ deterministically picks one graph reachable from G by sequential rewriting.

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